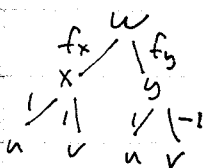


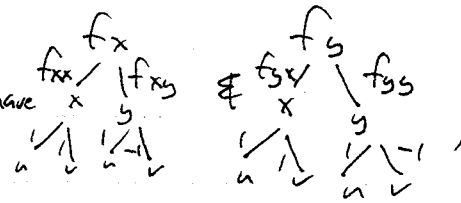
Math 18 Solns to selected hw problems, §§ 3.1-3.4, due 10/3/01

3.1 #12, 3.3 #2, 3.4 #20

3.1.1d



$$\frac{\partial w}{\partial v} = f_x \cdot 1 + f_y \cdot (-1) = f_x - f_y$$



so  $\frac{\partial^2 w}{\partial u \partial v} = \frac{\partial}{\partial u} \left( \frac{\partial w}{\partial v} \right) = \frac{\partial}{\partial u} (f_x - f_y) = f_{xx} \cdot 1 + f_{xy} \cdot 1 - (f_{yx} \cdot 1 + f_{yy} \cdot 1)$   
 $= f_{xx} + f_{xy} - f_{yx} - f_{yy} = f_{xx} + f_{yy}$  (assuming  $f$  is of class  $C^2$ ).

3.3d

$$f(x,y) = x^2 + y^2 - xy \quad f_x = 2x - y \quad f_y = 2y - x$$

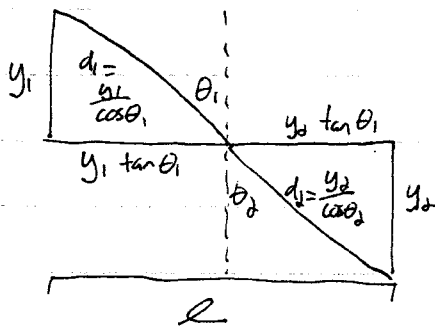
$Df(x,y) = [2x - y \quad 2y - x] = [0 \quad 0]$ , so  $2x - y = 0$  &  $x = 2y$ . Thus  $x = y = 0$  is the only critical pt.

$$A = f_{xx} = 2 \quad B = f_{xy} = -1 \quad C = f_{yy} = 2 \quad \Delta = AC - B^2 = 4 - 1 = 3$$

So  $(0,0)$  is a ~~not~~ local minimum.

3.4.20

Let  $l$  = horizontal distance b/w  $A$  &  $B$ ,  $y_1$  the vertical distance from  $A$  to the boundary, and  $y_2$  the vertical distance from  $B$  to the body. We have



Our constraint is  $g(\theta_1, \theta_2) = y_1 \tan \theta_1 + y_2 \tan \theta_2 = l$ .

We want to minimize the time, i.e.,  $\frac{d_1}{v_1} + \frac{d_2}{v_2} =$   
 $= \frac{y_1}{v_1 \cos \theta_1} + \frac{y_2}{v_2 \cos \theta_2} = f(\theta_1, \theta_2)$ .

$\nabla g(x,y) = (y_1 \sec^2 \theta_1, y_2 \sec^2 \theta_2)$ , which is never  $(0,0)$ .

So try to solve  $\nabla f(x,y) = \lambda \nabla g(x,y)$

$$\left( \frac{y_1}{v_1} \tan \theta_1 \sec \theta_1, \frac{y_2}{v_2} \tan \theta_2 \sec \theta_2 \right) = \lambda (y_1 \sec^2 \theta_1, y_2 \sec^2 \theta_2)$$

1<sup>st</sup> equation:  $\frac{y_1}{v_1} \tan \theta_1 \sec \theta_1 = \lambda y_1 \sec^2 \theta_1$  reduces to  $\frac{\sin \theta_1}{v_1} = \lambda$ .

Similarly, the 2<sup>nd</sup> equation reduces to  $\frac{\sin \theta_2}{v_2} = \lambda$ . Thus  $\frac{\sin \theta_1}{v_1} = \frac{\sin \theta_2}{v_2}$ ,

or  $\frac{\sin \theta_1}{\sin \theta_2} = \frac{v_1}{v_2}$ .