

1. Let  $A$  be a  $2 \times 2$  matrix with eigenvalues 1 and 2, and  $B$  a  $2 \times 2$  matrix with eigenvalues 0 and -7. Compute the eigenvalues of the following matrices, or prove that you don't have enough information.

(a)  $AB$

*Not enough info. If  $A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$  &  $B = \begin{bmatrix} 0 & 0 \\ 0 & -7 \end{bmatrix}$ , then  $AB$  has evs 0 & -14.*

*If  $B = \begin{bmatrix} -7 & 0 \\ 0 & 0 \end{bmatrix}$ , then  $AB$  has evs -7 & 0.*

(b)  $A^T$     1, 2

(c)  $A^{-1}$      $\frac{1}{1} = 1$      $\notin \frac{1}{2}$

(d)  $A+B$     *Not enough info. Same example as (a).*

(e)  $A^2$      $1^2 = 1$      $\notin 2^2 = 4$

(f)  $I_2 + A$      $1+1=2$      $1+2=3$

*(If  $A\vec{x} = \lambda\vec{x}$ , then  $(I_2 + A)\vec{x} = \vec{x} + \lambda\vec{x} = (1+\lambda)\vec{x}$ )*

2. Let  $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ . Show that the product  $\langle \vec{x}, \vec{y} \rangle = (A\vec{x}) \cdot (A\vec{y})$  (where  $\cdot$  is the usual dot product) is *not* an inner product on  $\mathbb{R}^2$ .

The problem is that  $A$  is singular.

$$\langle \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \rangle = A \begin{bmatrix} 1 \\ -1 \end{bmatrix} \cdot A \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \vec{0} \cdot \vec{0} = 0.$$

But the inner product of a nonzero vector with itself can't be 0.

3. (a) Give an example of a vector space  $V$  and a linear transformation  $T : V \rightarrow V$  that is one-one but not onto.

$$V = \{(a_1, a_2, a_3, \dots) \mid a_i \in \mathbb{R}\} = \text{all infinite sequences}$$

$$T(a_1, a_2, \dots) = (a_1, 0, a_2, 0, \dots)$$

(There are other answers.)

- (b) Give an example of a vector space  $W$  and a linear transformation  $S : W \rightarrow W$  that is onto but not one-to-one.

Same  $V$ .

$$S(a_1, a_2, \dots) = (a_2, a_3, \dots)$$

(There are other answers.)

4. Find the area of the parallelogram with vertices  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ ,  $\begin{bmatrix} 2 \\ 7 \end{bmatrix}$ ,  $\begin{bmatrix} 5 \\ 10 \end{bmatrix}$ , and  $\begin{bmatrix} 4 \\ 5 \end{bmatrix}$ .

$$\text{Area} = \left| \det \begin{bmatrix} \vec{u} & \vec{v} \end{bmatrix} \right|$$

$$\vec{u} = \begin{bmatrix} 1 \\ 7 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 6 \end{bmatrix}$$

$$\vec{v} = \begin{bmatrix} 4 \\ 5 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

$$\text{So Area} = \left| \det \begin{bmatrix} 1 & 3 \\ 6 & 4 \end{bmatrix} \right| = |3 - 15| = 12.$$

5. Let  $A$  be a complex  $n \times n$  diagonalizable matrix. Show that  $A$  has a cube root. (That is, show that there exists a complex  $n \times n$  matrix  $B$  such that  $B^3 = A$ .)

$$A = SDS^{-1}, \text{ where } D = \begin{bmatrix} d_1 & & 0 \\ & \ddots & \\ 0 & & d_n \end{bmatrix}$$

Every complex number has at least one cube root. For each  $i$ , let  $\mu_i$  be a cube root of  $d_i$  (i.e.,  $\mu_i^3 = d_i$ ).

Now let  $M = \begin{bmatrix} \mu_1 & & 0 \\ & \ddots & \\ 0 & & \mu_n \end{bmatrix}$ . Then  $M^3 = D$ , and

$$(SMS^{-1})^3 = SMS^3S^{-1} = SD(S^{-1})^3 = A.$$

So  $SMS^{-1}$  is a cube root of  $A$ .

6. Let  $A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix}$ . Because it's nice to be nice, I inform you that the reduced echelon form of  $A$  is  $\begin{bmatrix} 1 & -2 & 0 & -1 & 3 \\ 0 & 0 & 1 & 2 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$ .

(a) Find a basis for  $\text{Im } A$ .

The pivot columns of  $\text{rref } A$  are the 1<sup>st</sup> and the third, so the 1<sup>st</sup> & 3<sup>rd</sup> columns of  $A$  form a basis of the column space of  $A$ , which is the same as  $\text{Im } A$ .

$$\text{basis : } \left\{ \begin{bmatrix} -3 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 5 \end{bmatrix} \right\}$$

(b) Find a basis for  $\text{Ker } A$ .

$$\text{Sols. of } A\vec{x} = \vec{0} \text{ satisfy } x_1 - 2x_2 - x_4 + 3x_5 = 0 \\ x_3 + 2x_4 - 2x_5 = 0,$$

or  $x_1 = 2x_2 + x_4 - 3x_5$   
 $x_3 = -2x_4 + 2x_5$ . So solns are of the form

$$\begin{bmatrix} 2x_2 + x_4 - 3x_5 \\ x_2 \\ -2x_4 + 2x_5 \\ x_4 \\ x_5 \end{bmatrix}, \text{ or } x_2 \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -3 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix}.$$

$$\text{basis : } \left\{ \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix} \right\}$$

7. As usual, let  $M_{n \times n}$  be the space of  $n \times n$  matrices. Define a transformation  $T : M_{n \times n} \rightarrow M_{n \times n}$  by  $T(A) = \text{trace}(A)$ .

(a) Show that  $T$  is linear.

$$\begin{aligned}\text{trace}(aA + bB) &= \text{sum of diagonal entries of } aA + bB \\ &= (\text{sum of diag. entries of } aA) + (\text{sum of diag. entries of } bB) \\ &= a \cdot (\text{sum of diag. entries of } A) + b \cdot (\text{sum of diag. entries of } B) \\ &= a \cdot \text{trace}(A) + b \cdot \text{trace}(B)\end{aligned}$$

(b) What is the dimension of  $\ker T$ ?  $T : M_{n \times n} \rightarrow \mathbb{R}$

We know that  $\dim(\text{Im } T) + \dim(\ker T) = \dim(M_{n \times n})$ .

$T$  is onto, so  $\text{Im } T = \mathbb{R}$  &  $\dim(\text{Im } T) = 1$ , and  $\dim(M_{n \times n}) = n^2$ .

So ~~also~~  $1 + \dim(\ker T) = n^2$   
 $\dim(\ker T) = n^2 - 1$ .

(c) Find a basis for  $\ker T$  in the case  $n = 2$ .

We need  $2^2 - 1 = 3$  lin. ind. matrices with trace 0.

One answer:  $\left\{ \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \right\}$

8. Do one of the following problems. Make sure that I can tell which one you're doing.

- (a) Determine whether the following statement is true or false. If it's true, prove it; if it's false, give a counterexample.

STATEMENT: Let  $T$  be a linear transformation. If the set  $\{T(\vec{v}_1), \dots, T(\vec{v}_n)\}$  is linearly independent, then so is the set  $\{\vec{v}_1, \dots, \vec{v}_n\}$ .

- (b) Let  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear transformation. Show that there exists a unique  $m \times n$  matrix  $M_T$  such that  $T(\vec{x}) = M_T \vec{x}$  for all  $\vec{x} \in \mathbb{R}^n$ .

- (c) Let  $A$  be an  $m \times n$  matrix. Show that  $\ker A = \ker A^T A$ .

(a) True. Say  $c_1 \vec{v}_1 + \dots + c_n \vec{v}_n = \vec{0}$ . Then, by linearity,  
 $c_1 T(\vec{v}_1) + \dots + c_n T(\vec{v}_n) = \vec{0}$ . Since the  $T(\vec{v}_i)$ 's are linearly ind.,  
 $c_1 = c_2 = \dots = c_n = 0$ .

(b) Take  $M_T = \begin{bmatrix} T(\vec{e}_1) & \dots & T(\vec{e}_n) \end{bmatrix}$ , where the  $\vec{e}_i$ 's are the standard basis vectors in  $\mathbb{R}^n$ . Then  $M_T \vec{e}_i = T(\vec{e}_i)$  for all  $i$ , and  $M_T$  is the only matrix with this property. Since any  $\vec{x} \in \mathbb{R}^n$  can be written in terms of the  $\vec{e}_i$ 's,  $M_T \vec{x} = T(\vec{x})$ , by linearity.

(c)  $\vec{x} \in \ker A^T A \iff A^T A \vec{x} = \vec{0}$   
 $\iff A^T(A\vec{x}) = \vec{0}$   
 $\iff A\vec{x} \in (\ker A)^{\perp} \cap (\ker A^T)^{\perp}$ . Since  $\ker A$  &  $\ker A^T$  are orthogonal complements, their intersection is  $\{0\}$ ,  
 $\therefore A\vec{x} = \vec{0}$   
 $\iff \vec{x} \in \ker A$ .

9. Find the equation  $y = mx + b$  of the line that best fits the data points  $(1, 2)$ ,  $(2, 1)$ ,  $(3, 1)$ , and  $(4, -1)$ .

"Solve"  $m \cdot 1 + b = 2$   
 $m \cdot 2 + b = 1$   
 $m \cdot 3 + b = 1$   
 $m \cdot 4 + b = -1$ , or  $\begin{bmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 1 \\ -1 \end{bmatrix}$

$$A \vec{x} = \vec{c}$$

The least-squares soln  $\vec{x}^*$  satisfies  $A^T A \vec{x}^* = A^T \vec{c}$ , or

$$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 1 & 1 & 1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \\ 4 & 1 \end{bmatrix} \vec{x}^* = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 1 & 1 & 1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 1 \\ -1 \end{bmatrix}$$

$$\begin{bmatrix} 30 & 10 \\ 10 & 4 \end{bmatrix} \vec{x}^* = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$$

Row reduce  $\begin{bmatrix} 30 & 10 & : & 3 \\ 10 & 4 & : & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1/3 & : & 1/10 \\ 10 & 4 & : & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1/3 & : & 1/10 \\ 0 & 2/3 & : & 2 \end{bmatrix}$

$\rightarrow \begin{bmatrix} 1 & 0 & : & -9/10 \\ 0 & 1 & : & 3 \end{bmatrix}$ . So  $m^* = -9/10$ ,  $b^* = 3$ , & the line  
is  $y = -9/10 x + 3$

(EXTRA CREDIT) An  $n \times n$  matrix  $A$  is called *skew-symmetric* if  $A^T = -A$ . Show that all the eigenvalues of a skew-symmetric matrix are pure imaginary. (That is, if  $a + bi$  is an eigenvalue, then  $a = 0$ .)

Sq  $A\vec{x} = \lambda\vec{x}$  ( $\vec{x} \neq \vec{0}$  may be complex) ( $\vec{x} \neq \vec{0}$ )

Then  $\langle \vec{x}, A\vec{x} \rangle = \langle \vec{x}, \lambda\vec{x} \rangle = \bar{\lambda} \langle \vec{x}, \vec{x} \rangle$ .

Also,  $\langle \vec{x}, A\vec{x} \rangle = \vec{x}^T (\overline{A\vec{x}}) = \vec{x}^T \overline{A} \overline{\vec{x}} = \vec{x}^T A \overline{\vec{x}}$  (since  $A$  is real)

=  $\vec{x}^T (-A^T) \overline{\vec{x}}$  (since  $A$  is skew-symmetric)

=  $-\vec{x}^T A^T \overline{\vec{x}} = -(A\vec{x})^T \overline{\vec{x}} = \cancel{-(\lambda\vec{x})^T \overline{\vec{x}}} = -\lambda \langle \vec{x}, \vec{x} \rangle$ .

So  $\bar{\lambda} \langle \vec{x}, \vec{x} \rangle = -\lambda \langle \vec{x}, \vec{x} \rangle$ . Since  $\vec{x} \neq \vec{0}$ ,  $\langle \vec{x}, \vec{x} \rangle \neq 0$ , so

$\bar{\lambda} = -\lambda$ , ~~which means that  $\lambda$  is real~~  
which means that  $\lambda$  is pure imaginary.